

Lecture 28

14.6. Triple Integrals and Applications

- Goals:** (1) Use a triple integral to find the volume of a solid region.
 (2) Find the center of mass and moments of inertia of a solid region.

Questions:

- What is Fubini's Theorem for double integrals?
- How to find the center of mass for planar region?

14.6.1. Triple integrals

- (1) Definition of triple integral:

If f is a continuous function over a bounded solid region Q , then the **triple integral of f over Q** is defined as

$$\iiint_Q f(x, y, z) dV = \lim_{\|\Delta\| \rightarrow 0} \sum_{i=1}^n f(x_i, y_i, z_i) \Delta V_i$$

provided the limit exists.

In particular, the volume of the solid region Q is given by

$$\text{Volume of } Q = \iiint_Q dV$$

- (2) Properties of triple integrals

$$1. \iiint_Q cf(x, y, z) dV = c \iiint_Q f(x, y, z) dV$$

$$2. \iiint_Q [f(x, y, z) \pm g(x, y, z)] dV = \iiint_Q f(x, y, z) dV \pm \iiint_Q g(x, y, z) dV$$

$$3. \iiint_Q f(x, y, z) dV = \iiint_{Q_1} f(x, y, z) dV + \iiint_{Q_2} f(x, y, z) dV$$

where Q is union of two non-overlapping solid subregions Q_1 and Q_2 .

- (3) Fubini's Theorem on triple integrals

Let f be continuous on a solid region Q defined by

$$a \leq x \leq b, \quad h_1(x) \leq y \leq h_2(x), \quad g_1(x, y) \leq z \leq g_2(x, y)$$

where h_1, h_2, g_1 , and g_2 are continuous functions. Then,

$$\iiint_Q f(x, y, z) dV = \int_a^b \int_{h_1(x)}^{h_2(x)} \int_{g_1(x, y)}^{g_2(x, y)} f(x, y, z) dz dy dx.$$

Note: there are 5 more similar iterated triple integral formulas. Can you list all of them?

- (4) Example 1: evaluating triple integral (p. 1028)
Try exercises 1-8
- (5) Example 2: finding volume by using triple integral (p. 1029)
Try exercises 23-26
- (6) Example 3: changing the order of integration (p. 1030)
Try exercises 27-32
- (7) Example 4: determining the limits of integration (p. 1031)
Try exercises 13-18

14.6.2. Center of mass

- (1) Definition of mass:

If ρ is a continuous density function on a solid region Q , then the mass m of the solid is given by

$$m = \iiint_Q \rho(x, y, z) dV$$

Note: this is the same formula for triple integral.

- (2) Define three moments of mass by triple integrals:

$$M_{yz} = \iiint_Q x\rho(x, y, z) dV$$

$$M_{zx} = \iiint_Q y\rho(x, y, z) dV$$

$$M_{xy} = \iiint_Q z\rho(x, y, z) dV$$

- (3) The center of mass is given by

$$\bar{x} = \frac{M_{yz}}{m}, \quad \bar{y} = \frac{M_{zx}}{m}, \quad \bar{z} = \frac{M_{xy}}{m}.$$

Note: if the density function is constant, then the center of mass is also called the **centroid**.

- (4) Example 5: finding the center of mass for solid region (p. 1033)
Try exercises 39-44.

14.6.3. Moments of inertia

(1) First moments.

The moments of mass M_{yz} , M_{zx} , and M_{xy} are also called the **first moments** about yz -plane, zx -plane, and xy -plane, respectively.

(2) Second moments are also called the **moments of inertia** of a solid region about x -axis, y -axis, and z -axis, respectively:

$$I_x = \iiint_Q (y^2 + z^2) \rho(x, y, z) dV$$

$$I_y = \iiint_Q (z^2 + x^2) \rho(x, y, z) dV$$

$$I_z = \iiint_Q (x^2 + y^2) \rho(x, y, z) dV$$

Note: usually we find three intermediate triple integrals in order to find the above moments of inertia:

$$I_{yz} = \iiint_Q x^2 \rho(x, y, z) dV$$

$$I_{zx} = \iiint_Q y^2 \rho(x, y, z) dV$$

$$I_{xy} = \iiint_Q z^2 \rho(x, y, z) dV$$

Then $I_x = I_{yz} + I_{xy}$, $I_y = I_{zx} + I_{xy}$, and $I_z = I_{yz} + I_{zx}$.

(3) Example 6: finding the moments of inertia (p. 1034)

Try exercises 55-58

14.6.4. **Homework Set #28**

- Read 14.6 (pages 1027-1034).
- Do exercises on pages 1035-1037:
1, 3, 5, 7, 13, 15, 17, 19, 21, 23, 25, 27, 29, 31, 33, 35, 37, 39, 41, 61, 63