

Lecture 12

12.5. Arc Length and Curvature

- Goals:**
- (1) Find the arc length of a space curve.
 - (2) Use the arc length parameter to describe a plane curve or space curve.
 - (3) Find the curvature of a curve at a point on the curve.
 - (4) Use a vector-valued function to find frictional force.

Questions:

- What is the formula for the length of a smooth plane curve C given by the parametric equations $x = x(t)$, $y = y(t)$ on an interval $[a, b]$?

Answer: $s = \int_a^b \sqrt{[x'(t)]^2 + [y'(t)]^2} dt.$

- What is the formula, if the curve is given in vector form, that is, $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j}$?

Answer: $s = \int_a^b \|\vec{r}'(t)\| dt.$

Try exercises 1-6 (p. 877)

- Recall:

$$\vec{T}(s) = \frac{\vec{r}'(s)}{\|\vec{r}'(s)\|} \text{ is the unit tangent vector of } \vec{r}(s).$$

$$\vec{a}(t) = a_T \vec{T}(t) + a_N \vec{N}(t) \text{ is the decomposition of acceleration.}$$

12.5.1. Arc length of a space curve

- (1) If C is a smooth curve (in space) given by $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$, on an interval $[a, b]$, then the arc length of C on the interval is:

$$s = \int_a^b \|\vec{r}'(t)\| dt = \int_a^b \sqrt{[x'(t)]^2 + [y'(t)]^2 + [z'(t)]^2} dt$$

- (2) Examples 1, 2: finding the arc length of a curve in space (pp. 869-870).
 - Try exercises 9-14

12.5.2. Arc length parameter

Curves can be represented by vector-valued functions in different way, depending upon the choice of parameter. For *motion* along a curve, the convenient parameter is time t , while for studying *geometric properties* of a curve, the convenient parameter is arc length s .

- (1) Definition: Let C be a smooth curve given by $\vec{r}(t)$ on a closed interval $[a, b]$. For $a \leq t \leq b$, the **arc length function** is given by

$$s(t) = \int_a^t \|\vec{r}'(w)\| dw = \int_a^t \sqrt{[x'(w)]^2 + [y'(w)]^2 + [z'(w)]^2} dw$$

Note: $s(t) \geq 0$. It's also called arc length parameter. It measures the distance along C from the initial point $(x(a), y(a), z(a))$ to $(x(t), y(t), z(t))$.

(2) By the Second Fundamental Theorem of Calculus,

$$\frac{ds}{dt} = \|\vec{r}'(t)\|, \text{ or}$$

$$ds = \|\vec{r}'(t)\| dt.$$

Note: The second formula is in differential form. Now if we choose s as the parameter, that is, $\vec{r}(s) = x(s)\vec{i} + y(s)\vec{j} + z(s)\vec{k}$, then $\|\vec{r}'(s)\| = 1$.

On the other hand, if $\|\vec{r}'(t)\| = \frac{ds}{dt} = 1$, then t must be the arc length parameter. Therefore, the parameter t is the arc length parameter if and only if $\|\vec{r}'(t)\| = 1$.

(3) Example 3: finding the arc length function for a line (p. 871).

Hint: solve for t in terms of s .

- Try exercises 19, 20

12.5.3. Curvature

Another important use of the arc length parameter is to find curvature—the measure of how sharply a curve bends.

(1) Definition: Let C be a smooth curve given by $\vec{r}(s)$ where s is the arc length parameter. The curvature K at s is given by

$$K = \left\| \frac{d\vec{T}}{ds} \right\| = \|\vec{T}'(s)\|.$$

(2) In general, if the parameter is t (not necessary to be s), then the curvature at t is given by

$$K = \frac{\|\vec{T}'(t)\|}{\|\vec{r}'(t)\|} = \frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^3}.$$

(3) Example 5: finding the curvature of a space curve (p. 873).

- Try exercises 21-40

(4) In particular, if C is given by a regular (rectangular coordinates) function $y = f(x)$, then the curvature at $P(x, y)$ is given by

$$K = \frac{|y''|}{[1 + (y')^2]^{3/2}}$$

- Proof: $\vec{r}(t) = x\vec{i} + f(x)\vec{j} + 0\vec{k}$, $\vec{r}'(t) = \vec{i} + f'(x)\vec{j}$, and $\vec{r}''(t) = f''(x)\vec{j}$. So $\vec{r}'(t) \times \vec{r}''(t) = f''(x)\vec{k}$.

- Definition: The circle (on the concave side of the curve) with center P and radius $r = 1/K$ is called the **circle of curvature** (See Figure 12.36 or 12.37). P is called the *center of curvature*, r is called the *radius of curvature* at P .

(5) Example 6: finding the curvature of a plane curve (p. 874).

- Try exercises 41-44, 45-54

(6) Relationship among acceleration, speed, and curvature.

$$\vec{a}(t) = \frac{d^2s}{dt^2} \vec{T} + K \left(\frac{ds}{dt} \right)^2 \vec{N}$$

(7) Example 7: finding the tangential and normal components of acceleration (p. 875).

- Try exercise 96

(8) Application in physics and engineering dynamics: frictional force

$$\vec{F} = m\vec{a} = m \frac{d^2s}{dt^2} \vec{T} + mK \left(\frac{ds}{dt} \right)^2 \vec{N}$$

$mK \left(\frac{ds}{dt} \right)^2$ is called the *force of friction*.

(9) Example 8: finding frictional force (p. 876).

- Try exercises 97-98

(10) Summary: p. 877. This is a very important list of formulas.

12.5.4. Homework Set #12

- Read 12.5 (pages 869-877).
- Do exercises on pages 877-880:
1, 3, 5, 7, 9, 11, 13, 21, 23, 27, 29, 31, 33, 35, 37, 41, 43, 87, 97, 101-104